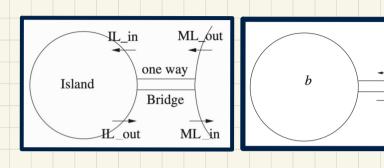
Bridge Controller: Guards of "old" Events 1st Refinement



constants: d

axioms:

 $axm0_1: d \in \mathbb{N}$

 $axm0_2: d > 0$

variables: a, b, c

invariants:

inv1 $_{-}$ 1 : $a \in \mathbb{N}$

inv1_2 : $b \in \mathbb{N}$

inv1_3 : $c \in \mathbb{N}$

 $inv1_4: a+b+c=n$

inv1_**5**: $a = 0 \lor c = 0$

ML_out: A car exits mainland (getting on the bridge).

ML_out when ?? then a := a + 1 end

ML_in: A car enters mainland (getting off the bridge).

Bridge Controller: Abstract vs. Concrete State Transitions

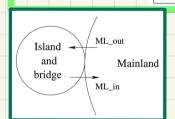
Abstract m0

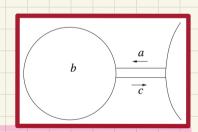
variables: n

invariants: $n \in \mathbb{N}$

 $inv0_2 : n < d$

ML_out **when** *n* < *d* **then** *n* := *n* + 1 **end** ML_in
when
n > 0
then
n := n - 1
end





Concrete m1

variables: a, b, c

invariants: $\mathbf{inv1}_{-1} : \mathbf{a} \in \mathbb{N}$

 $inv1_2: b \in \mathbb{N}$

inv1_3 : *c* ∈ N

inv1_4: a+b+c=n**inv1_5**: $a=0 \lor c=0$ c = 0 **then** a := a + 1 **end**

a+b < d

ML_out

when

ML_in when c > 0 then c := c - 1 end

d = 2 n =

d = 2n initialized to 0

Scenario

- car leaving ML
- car entering ML

d = 2 a, b, c initialized to 0



Before-After Predicates of Event Actions: 1st Refinement

 $\begin{array}{c|c} \mathsf{ML_in} \\ \mathbf{when} \\ 0 < c \\ \mathbf{then} \\ c := c-1 \\ \mathbf{end} \end{array}$

 $egin{aligned} \mathsf{ML_out} \\ \mathbf{when} \\ a+b < d \\ c = 0 \\ \mathbf{then} \\ a := a+1 \\ \mathbf{end} \end{aligned}$

Pre-StatePost-StateSate Transition

Before–after $a'=a \ \land \ b'=b \ \land$ predicates c'=c-1

$$\begin{vmatrix} a' = a + 1 & \land & b' = b \land \\ c' = c & \end{vmatrix}$$

States, Invariants, Events: Abstract vs. Concrete

Abstract mo

variables: n

invariants:

inv0 1 : $n \in \mathbb{N}$ inv0.2: n < d ML out when n < d

then

n := n + 1end

then n := n - 1end

 ML_{in}

when

then

c > 0

n > 0

 ML_{in}

when

axioms:

 $axm0_1: d \in \mathbb{N}$ axm0 2: d > 0

constants: d

Concrete m1

variables: a, b, c

invariants:

 $inv1_1: a \in \mathbb{N}$

inv1_2: $b \in \mathbb{N}$ inv1 3 : $c \in \mathbb{N}$

inv1 4: a+b+c=n

inv1_5: $a = 0 \lor c = 0$

ML out when a+b < d

c = 0then

a := a + 1end

c := c - 1end

PO Rule of Invariant Preservation in Refinement: Components



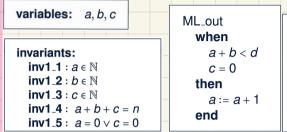


ML out when n < dthen

when n > 0then n := n + 1n := n - 1end end

ML in

Concrete m1



ML in when c > 0then c := c - 1end

v and v': abstract variables in pre-/post-states w and w': concrete variables in pre-/post-states G(c, v): an abstract event's quards H(c, w): a concrete event's quards

I(c, v): list of abstract invariants

J(c, v, w): list of concrete invariants

E(c, v): an abstract event's effect F(c, w): a concrete event's effect

PO/VC Rule of Guard Strengthening: Sequents

Abstract m0

variables: n

invariants: inv0_1 : $n \in \mathbb{N}$ inv0_2 : $n \le d$ ML_out **when** *n* < *d* **then** *n* := *n* + 1 **end** ML_in when n > 0 then n := n − 1 end

ML_in

when

then

end

c > 0

c := c - 1

Concrete m1

variables: a, b, c

invariants: inv1 1 : $a \in \mathbb{N}$

 $inv1_2: b \in \mathbb{N}$

inv1_3 : $c \in \mathbb{N}$ inv1_4 : a+b+c=n

a + b + c = n a + b + c = na + b + c = n ML_out when a + b < d c = 0 then a := a + 1

end

A(c) $I(c, \mathbf{v})$ $J(c, \mathbf{v}, \mathbf{w})$ $H(c, \mathbf{w})$ \vdash $G_i(c, \mathbf{v})$

Q. How many PO/VC rules for model m1?

Discharging POs of m1: Guard Strengthening in Refinement

ML_out/GRD

 $d \in \mathbb{N}$ d > 0 $n \in \mathbb{N}$ n < d $a \in \mathbb{N}$ $b \in \mathbb{N}$ $\boldsymbol{c} \in \mathbb{N}$ a+b+c=n $a = 0 \lor c = 0$ a+b < dc = 0n < d

 $\frac{H1 \vdash G}{H1, H2 \vdash G} \quad MON$

 $\frac{H(\mathbf{F}), \mathbf{E} = \mathbf{F} \vdash P(\mathbf{F})}{H(\mathbf{E}), \mathbf{E} = \mathbf{F} \vdash P(\mathbf{E})} \quad \mathbf{EQ_LR}$

 $H,P \vdash P$

Discharging POs of m1: Guard Strengthening in Refinement

ML_in/GRD

 $d \in \mathbb{N}$ d > 0 $n \in \mathbb{N}$ n < d $a \in \mathbb{N}$ $b \in \mathbb{N}$ $\boldsymbol{c} \in \mathbb{N}$ a+b+c=n $a = 0 \lor c = 0$ c > 0

n > 0

 $\frac{H1 \vdash G}{H1, H2 \vdash G} \quad MON$ $H(F), E = F \vdash P(F)$

 $H,P \vdash P$ HYP $\bot \vdash P$ FALSE_L

 $H(\mathbf{F}), \mathbf{E} = \mathbf{F} \vdash P(\mathbf{F})$ $H(\mathbf{E}), \mathbf{E} = \mathbf{F} \vdash P(\mathbf{E})$

- EQ_LR

 $H,P \vdash R \qquad H,Q \vdash R$ $H,P \lor Q \vdash R$

– OR₋L